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Dynamics - Lesson

*2: Rectilinear
Motion Example*

Problem Problem

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Problem

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Problem

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Problem

~~2-17/2-18/2-19/~~

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~~Dynamics. FE Exam~~

Mechanics Of

Materials - Internal

Torque At Point B

and C Simple

problem on

resultant force

[2015] Dynamics

01: Introduction

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**Overview [with
closed caption]**

~~ME 274: Dynamics:~~

~~Review of Chapters
12, 13, and 14~~

~~Statics—3D vector
projection—~~

~~example~~

Dynamics

Lecture 03:

Particle

kinematics,

Rectilinear

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continuous
motion part 2

~~Moment of Force~~

~~Problem 1 Statics~~

~~Moment in 2D~~

~~example problem~~

Statics - 3D force

balance [The easy
way] (Request)

Finding the

Components of a

Force or Vector

Problem

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Problem 2-1/

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Dynamics. Problem

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Problem

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Step 1 of 2.

Determine the

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positions of points
A and B from the
given graph with
respect to x and y
coordinates. A (1,
2) B (5, 1)

Calculate the
position, from point
B to point A along x
-axis as shown:

Here, the x
-coordinate of point
B is , and the x
-coordinate of point

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A is. Substitute for ,
and for .

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Problem 2.2 Add
the two vectors
shown to form a
resultant vector

RE, and report your
result using polar
vector

representation.

Solution Part (a)

The vector polygon
shown at the right
corresponds to...

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Multiply the scalar form of Eq. (1.2) on page 7 (i.e., $a = dv/dt$) by dt , and integrate both sides to show that the velocity v (also a scalar) is constant. Then use the scalar form of

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Eq. (1.1) to show that the (scalar) position r is a linear function of time.

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