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We have $F_3(p, Q) = (eQ - 1)^2 \tan p$ so $\frac{\partial F_3}{\partial Q} = 2eQ (eQ - 1) \tan p$
 $\frac{\partial Q}{\partial p} \frac{\partial F_3}{\partial Q} = (eQ - 1)^2 \sec^2 p$. The second of these may

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be solved to yield Q in terms of q and p : $P = \frac{1}{2} Q = \log(1 + q^{1/2} \cos p)$ and then we may plug this back into the equation for P to obtain $P = 2q^{1/2} \sin p + q \sin 2p$ as advertised.

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Classical refers to the
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mechanics. Velocity:

$dr v = \cdot dt$ Linear

momentum: $p =$

mv . Force: $dp F = \cdot dt$ In

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Most cases, mass is constant and force is simplified:
 $F = \frac{d}{dt}(mv) = m \frac{dv}{dt}$

Acceleration: $a = \frac{dv}{dt}$
 $F = ma$ Newtons
second law of motion holds in a reference frame that is inertial or Galilean.
Angular Momentum: $L = r \times p$
Torque: $T = r \times F$
Torque is the time derivative of angular

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Momentum: 1

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$k(1 - x)dx + 2E - x^2 - (2 - x)^2 \sin x$. where x is the ratio of ϕ/π and E is the energy. Answer:

The differential cross section is given by Goldstein (3.93): $s ds$

$$\sigma(\theta) = \sin \theta d\theta \quad W_e$$

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must solve for s , and $ds/d\phi$. Lets solve for ϕ (s) first, take its derivative with respect to s , and invert it to find $ds/d\phi$.

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equations between

two sets of

coordinates are $Q =$

$\log(1 + q^{1/2} \cos p)$ $P =$

$2(1 + q^{1/2} \cos p)q$

$1/2 \sin p$ (a) Show

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transformation
equations that Q, P
are canonical
variables if q and p
are. Page 2/5.

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