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The solution is $x(t) = 0.25e^{-2t} + 0.25 + 0.5t e^{-t}$ $t^2 + 2t + 2$ $[r,p,k] = \text{residue}([4,3],[1,6,34,0])$ The result is $r = [-0.0441 - 0.3735i, -0.0441 + 0.3735i, 0.0882]$, $p = [-3.0000 + 5.0000i, -3.0000 - 5.0000i, 0]$, and $k = []$. The solution is $x(t) = (0.0441 - 0.3735j)e^{(3+5j)t} + (0.0441 + 0.3735j)e^{(3-5j)t} + 0.0882$
The solution is $x(t) = 2e^{-3t} (0.0441 \cos 5t + 0.3735 \sin 5t) + 0.0882$ (continued on the next page)

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The characteristic equation derived earlier becomes $s^2 + 2s + 3 = 0$ whose roots are $s = -1 \pm j0.82$. The dominant time constant is $1/0.82 = 0.262$, and thus we would expect the steady-state response to be reached in about $4(0.262) = 1.04$ s. The scope plot confirms this. 16.

System Dynamics, Third Edition

Sample questions asked in the 3rd edition of System Dynamics: Consider the two-mass model shown in Figure P11.50. Use the following numerical values: $m_1 = m_2 = 1$, $k_1 = 1$, $k_2 = 4$, and $c_2 = 8$. a. Use MATLAB to obtain the root locus plot in terms of the parameter c_1 . b.

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1) You can substitute the form (5) into the differential equation and use the initial conditions to obtain equations for the coefficients. 2) You can use (1) and (2) to create a partial fraction expansion of (4) in terms of the complex factors. 3) You can perform an expansion in terms of the six roots, of the form A_1 .

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